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ON SOME STOCHASTIC GROWTH MODELS WITH APPLICATIONS

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ABSTRACT: In this paper, we consider some stochastic dynamical systems. The stochastic processes related to these models are some different kinds of tumor cancer cells. The growth and diffusion of brain tumor cancer is also studied by using a non-linear stochastic diffusion model. The considered models are generalization of some deterministic models. In the frame of these stochastic models we are able to study the growth models for tumor cells under the influence of random perturbations. In general mathematical models help to predict the tumour size and optimize the treatment procedure in deterministic form, there are several models including exponential, dynamical systems, logistic, nonlinear diffusion equations that have been used to describe the behaviour of cancer cell growth amd proliferation. By using the stochastic analysis and the Adomian method we can study more general models.

KEYWORDS: stochastic dynamical systems, stochastic diffusion processes, ito integrals, tumor cancer cells, adomian method.

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INTRODUCTION

Different types of dynamical systems of cancer progression and treatment have already been constructed. For example there are many problems written on the subject of mathematical models in cancer chemotherapy such as Hannelore Liset and David Julitz [1], K.R. Fister and Pannetta [2], J.M. Murrary,[3] and many others. We mension also the papers [4-7]. In this paper, we shall study a stochastic dynamical system and a stochastic diffusion process. In section 2, we shall solve the considered stochastic dynamical sestem. Some properties are also studied. In section 3, we shall solve a nonlinear stochastic partial differential equation. In section 4 a nonlinear stochastic diffusion model related to brain cancer is studied. We shall use Adomian decomposition method to find the stochastic solution.

A stochastic dynamical system

Let: $(\Omega, \mathbb{F}, (\mathbb{A}_t)_{t \ge 0}, P)$ be a filtered probability space. Consider the following stochastic dynamical system.

$$dX = b(X) dt + B(X)dW(t),$$
(1)
$$t \in [0, a_2^{-1}], \text{ where; } X = \begin{bmatrix} T \\ N \\ L \end{bmatrix},$$

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$$b(X) = \begin{bmatrix} a_1 T (1 - a_2 T) - D(t) T \\ a_3 - a_4 N - a_5 NT \\ -a_6 L - a_7 L T + a_8 NT \end{bmatrix}, \\B(X) = \begin{bmatrix} \sigma_1 T & 0 & 0 \\ 0 & \sigma_2 N & 0 \\ 0 & 0 & \sigma_3 L \end{bmatrix}, \\W(t) = \begin{bmatrix} W_1(t) \\ W_2(t) \\ W_3(t) \end{bmatrix}, \qquad \sigma_i \in (-\infty, \infty), \ i = 1, 2, 3,$$

 W_1 , W_2 and W_3 are standared independent Weiner processes adapted to the filteration $(A_t)_{t\geq 0}$, See [8].

The stochastic process {T(t) : $t \ge 0$ } is the tumor cell population at time t, {N(t): $t \ge 0$ } is the total level of natural killer cells effectiveness at time t and {L(t): $t \ge 0$ } is the total level of tumor specific CD 8⁺ T cell effectiveness at time t, see [9 – 12]. The parameters $a_1, ..., a_8$ are positive and D(t) is given by

$$D(t) = a_7 \frac{(L/T)^c}{s + (L/T)^c}, \ c, s \ge 0.$$

_ ..

It is supposed that the expectations E $[T^2(0)]$, E $[N^2(0)]$ and E $[L^2(0)]$ exist. It is supposed also that the vector (T(0), N(0), L(0)) is independent of (W₁(t), W₂(t), W₃(t)). We shall find now a representation for T(t).

Set $T^* = T^{-1}$ and using the stochastic chain rule of Ito, we get: $dT^* = [a_1a_2 + (\sigma_1^2 - a_1 + D(t)) T^*] dt - \sigma_1 T^* dW_1(t).$ Thus; $T^*(t) = T^{-1}(0) \exp [\sigma_1 W_1(t) - \frac{1}{2} \sigma_1^2 t + \int_0^t f(\theta) d\theta] + a_1a_2 \int_0^t exp [\sigma_1 \{W_1(t) - W_1(\theta)\} \frac{1}{2} \sigma_1^2 (t - \theta) + \int_{\theta}^t f(r) dr] d\theta,$ Where; $f(r) = \sigma_1^2 - a_1 + D(r)$ Notice that $T^*(t)$ is almost surely, a.s., positive, Thus $T(t) = T^{*-1}(t)$

The total level of the natural killer cells N(t), is given by: N(t) = N(0) exp $[\sigma_2 W_2(t) - a_4 t - \frac{1}{2}\sigma_2^2 t - a_5\int_0^t T(\theta)] dt$ $+ a_3\int_0^t exp [\sigma_2 \{W_2(t) - W_2(\theta)\} - a_4(t-\theta) - \frac{1}{2}\sigma_2^2 (t-\theta) - a_5\int_{\theta}^t T(r) dr] dt$ The total level L(t) of tumor specific CD 8⁺ is given by: L(t) = L(0) exp $[\sigma_3 W_3(t) - a_7\int_0^t T(\theta) dt - a_6 t - \frac{1}{2}\sigma^2 t]$ $+ \int_0^t a_8 N(\theta) T(\theta) [exp \sigma_3 (W_3(t) - W_3(\theta)) - a_7\int_{\theta}^t T(r) dr - a_6(t-\theta) - \frac{1}{2}\sigma^2 (t-\theta)] d\theta$. Let us study the case when; s = 0, Notice that the processes

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 $W_1(t)$, $W_1(t)$ - $W_1(s)$, T(0) are independent and $\operatorname{E}\left[e^{\sigma_{i}W_{1}(t)}\right] = \exp\left[\frac{\sigma_{i}^{2}}{2}t\right],$ $\operatorname{E}\left[e^{\sigma_{i}(W_{1}(t) - W_{i}(s))}\right] = \exp\left[\frac{(t-s)\sigma_{i}^{2}}{2}\right],$ i = 1, 2, 3Thus; $E[T^{-1}(t)] = e^{(a_7 - a_1 + \sigma_1^2)t} E[T^{-1}(0)] + \frac{a_1 a_2}{a_7 - a_1 + \sigma_1^2} \left[e^{(a_7 - a_1 + \sigma_1^2)t} - 1 \right].$ It is clear that $T(t) \le T(0) \exp\left[\sigma_1 W_1(t) + \frac{1}{2} \sigma_1^2 t - \int_0^t f(\theta) d\theta\right].$ Thus: $E[T(t)] \le E(T(0)) e^{(a_1 - a_7) t}$. If $a_2 = 0$, we get $T(t) = T(0) \exp\left[\sigma_1 W_1(t) + \frac{1}{2} \sigma_1^2 t - \int_0^t f(\theta) d\theta\right].$ If $a_2 = s = 0$, we get E (T²(t)) = E (T²(0)) exp $[\sigma_1^2 t + 2 (a_1 - a_7)t]$. Notice that T(t) and W₂(t) are independent, thus $\mathbf{E}[\mathbf{N}(t)] = e^{-ta_4} \mathbf{E}(N(0)) \mathbf{E}\left[\exp\left\{-a_5 \int_0^t \mathbf{T}(\theta) \, \mathrm{d}\theta\right\}\right]$ $+a_3\int_0^t e^{-a_4(t-\theta)} \mathbb{E}\left[\exp\left\{-a_5\int_{\theta}^t T(r) \mathrm{d}r\right\}\right] \mathrm{d}\theta.$ It is easy to see that $E[N(t)] \le e^{-ta_7} E[N(0)] + \frac{a_3}{a_3} [1 - e^{-ta_4}].$ The product N(t)T(t) and $W_3(t)$ and also T(t) are indepent, thus $\mathbf{E} \left[\mathbf{L}(\mathbf{t}) \right] = \mathbf{E} \left[\mathbf{L}(0) \right] e^{-a_6 t} \mathbf{E} \left[-a_7 \int_{\theta}^{t} T(\theta) \, \mathrm{d}\theta \right]$ + $a_8 \int_a^t \mathbb{E} \left[N(\theta) \operatorname{T}(\theta) \exp \left\{ -a_7 \int_a^t T(r) \, \mathrm{d}r \right\} \right] e^{a_6(t-\theta)} \, \mathrm{d}\theta.$

A nonlinear stochastic diffusion model

In this section, we shall study the following nonlinear stochastic diffusion model;

$$u(\mathbf{x}, \mathbf{t}) = \mathbf{f}(\mathbf{x}) + \int_{0}^{t} a(\mathbf{x}) \mathbf{u}(\mathbf{x}, \mathbf{s}) \frac{\partial}{\partial x} \left[\frac{1}{u(\mathbf{x}, \mathbf{s})} \frac{\partial \mathbf{u}(\mathbf{x}, \mathbf{s})}{\partial x} \right] d\mathbf{s}$$
$$+ \int_{0}^{t} \left[\lambda \ln \frac{\mu}{u(\mathbf{x}, \mathbf{s})} - \mathbf{g} \left(\nu(\mathbf{s}) \right) \right] u(\mathbf{x}, \mathbf{s}) d\mathbf{s} + \sigma \int_{0}^{t} \mathbf{u}(\mathbf{x}, \mathbf{s}) dW(\mathbf{s})$$

Where W(t) is a standard Wiener process adapted to the filteration $(\mathbb{A}_t)_{t\geq 0}$, $\sigma \in (-\infty, \infty)$, λ and μ are positive parameters, f(x) and a(x) are given continuous bounded functions defined on $(-\infty, \infty)$. It is supposed that a(x) is positive for all $x \in (-\infty, \infty)$.

It is supposed also that g and v are maps from $(0, \infty) \times \Omega$ to $(0, \infty)$, that are measurable and adapted to the filtration $(\mathbf{A}_t)_{t\geq 0}$ and are a.s., locally bounded.

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The stochastic process $\{u(x, t): -\infty < x < \infty, t > 0\}$ may be thought as the concentration of brain cancer tumor cells at a location x and time t, u(x,0) = f(x) represents the initial deterministic state.

Consider the following two Brownian motions:

$$X_{1}(t) = \exp \left[-\sigma W(t)\right], X_{2}(t) = \exp \left[\sigma W(t)\right].$$
It is easy to see that:

$$d X_{1}(t) = \frac{\sigma^{2}}{2} X_{1}(t) dt - \sigma X_{1}(t) dW(t),$$

$$d X_{2}(t) = \frac{\sigma^{2}}{2} X_{2}(t) dt + \sigma X_{2}(t) dW(t),$$

$$X_{1}(0) = X_{2}(0) = 1.$$
Set $u^{*}(x, t) = X_{1}(t) u(x, t)$ and applying Ito's product rule formula, we get

$$du^{*}(x, t) = X_{1}(t) u(x, t) \text{ and applying Ito's product rule formula, we get
$$du^{*}(x, t) = X_{1} du(x, t) + u(x, t) dX_{1} - \sigma^{2} X_{1} u(x, t) dt.$$
Thus;

$$\frac{1}{u^{*}(x, t)} \frac{\partial u^{*}(x, t)}{\partial t} = a(x) \frac{\partial}{\partial x} \left[\frac{1}{u^{*}(x, t)} \frac{\partial u^{*}(x, t)}{\partial x}\right] + F(t) - \lambda \ln(u^{*}(x, t)),$$

$$u^{*}(x, 0) = f(x),$$
Where;
F(t) $= \frac{-\sigma^{2}}{2} + \lambda \ln \mu - g(v(t)) - \lambda \sigma W(t).$
Set $v(x, t) = e^{\lambda t} u^{*}(x, t)$, one gets:

$$\frac{\partial v(x, t)}{\partial t} = a(x) \frac{\partial^{2} v(x, t)}{\partial x^{2}} + e^{\lambda t} F(t),$$

$$v(x, 0) = \ln f(x)$$
Thus; $v(x, t)$ is given by

$$v(x, t) = \int_{-\infty}^{\infty} G(x, y, t) \ln f(y) dy + + \int_{0}^{1} \int_{-\infty}^{\infty} G(x, y, t) e^{\lambda s} F(s) dy ds.$$
Where G is the fundamental solution of the equation

$$\frac{\partial u}{\partial t} = a(x) \frac{\partial^{2} u}{\partial x^{2}}.$$
Since $\int_{-\infty}^{\infty} G(x, y, t) \ln f(y) dy + \int_{0}^{t} e^{\lambda s} F(s) ds,$
So;

$$u(x, t) = \exp \left[\sigma W(t) + e^{-\lambda t} v(x, t)\right],$$
For a.s., $\omega \in \Omega$, and all $t \ge 0, -\infty < x < \infty$. Thus we can find a subset $\Omega^{*} \subset \Omega$, with P
 $(\Omega^{*}) = 1$, such that formula (2) is valid for all $\omega \in \Omega^{*}, t \ge 0, -\infty < x < \infty$.
It is clear that
 $W(t) = \int_{0}^{t} e^{A(x-t)} dW(s) + \lambda \int_{0}^{t} e^{\lambda(s-t)} W(s) ds,$
(3)
for all $W \in \Omega^{*}$.$$

From (2) and (3) one gets $u(x, t) = \exp \left[V(t) - \int_0^t e^{\lambda(s-t)} g(\nu, s) \, ds + H(x, t) \right],$ Where

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$$\begin{split} \mathsf{V}(\mathsf{t}) &= \sigma \, \int_0^t e^{\lambda(\mathsf{s}-\mathsf{t})} \, dW(\mathsf{s}), \\ \mathsf{H}(\mathsf{x},\mathsf{t}) &= e^{-\lambda t} \, \int_{-\infty}^{\infty} \mathsf{G}(\mathsf{x},\mathsf{y},\mathsf{t}) \ln \mathsf{f}(y) \, \mathsf{dy} + \left[\frac{\sigma^2}{2} \left(1 - e^{-\lambda t}\right)\right] \ln \mu. \\ \text{Notice that V(t) is a Gausian process with mean zero. The variance of V(t) is given by \\ \mathsf{E}\left[V^2(t)\right] &= \mathsf{E}\left[\sigma^2 \, \int_0^t e^{\lambda(\mathsf{s}-\mathsf{t})} \, dW(\mathsf{s})\right]^2 = \sigma^2 \, \int_0^t e^{2\lambda(\mathsf{s}-\mathsf{t})} \, \mathsf{ds} = \\ &= \frac{\sigma^2}{2\lambda} \left(1 - e^{-2\lambda t}\right). \\ \text{Thus;} \\ \mathsf{E}\left[e^{V(t)}\right] &= \frac{1}{\sqrt{2\pi\gamma(t)}} \int_{-\infty}^{\infty} e^x \, e^{\frac{-x^2}{2\gamma(t)}} \, \mathsf{dx} = \exp\left[\frac{\gamma(t)}{2}\right], \\ \text{where;} \\ &\gamma(t) &= \frac{\sigma^2}{2\lambda} \left[1 - e^{-2\lambda t}\right]. \\ \text{If g and } \gamma \text{ are independent of W, then the expected number of tumor cells is given by } \\ \mathsf{E}\left[u(\mathsf{x},\mathsf{t})\right] &= \mathsf{E}\left[\exp\left\{\frac{1}{2}\gamma(t) + \mathsf{H}\left(\mathsf{x},\mathsf{t}\right)\right\}\right] \, \mathsf{E}\left[\exp\left\{-\int_0^t e^{\lambda(\mathsf{s}-\mathsf{t})} g\left(\gamma(s)\right) \, \mathsf{ds}\right\}\right]. \\ \text{It can be also compute all the moments of the stochastic process } \{u(\mathsf{x},\mathsf{t})\}: \\ &e^{-n\mathsf{H}(\mathsf{x},\mathsf{t})} \, \mathsf{E}\left[u^n(\mathsf{x},\mathsf{t})\right] = \\ &= \mathsf{E}\left[\exp\left\{\frac{1}{2}n^2\gamma(t)\right\}\right] \, \mathsf{E}\left[\exp\left\{\int_0^t n \, e^{\lambda(\mathsf{s}-\mathsf{t})} \, \mathsf{g} \, \mathsf{ds}\right\}\right]. \end{split}$$

A brain cancer model

Let V(R,T) be the concentration of brain tumor cells at a location R and time T. Consider now the Burgers equation;

 $\frac{\partial V(R,T)}{\partial T} = \frac{D}{R^2} \frac{\partial}{\partial R} \left[R^2 \frac{\partial V(R,T)}{\partial R} \right] - (p-k)F(T)V(R,T).$ (4) Where D is the diffusion coefficients (estimated at 0.0013.0)

Where D is the diffusion coefficients, (estimated at 0.0013 Cm^2 per day for glioblastoma multiform).

The constants p and k represent proliferations rate and killing rate respectively, (R measures the distance from the origin of glioblastoma). The function F(T) describes to the temporal profile of the treatment.

Equation (5) can be written in the form

$$\frac{\partial u(x,t)}{\partial t} = a \frac{\partial^2 u(x,t)}{\partial x^2} - c(t) u(x,t), \qquad (5)$$

where $t = (p-k) T$, $p > k$,
 $x = \sqrt{\frac{a(p-k)}{D}}R$, $c(t) = F(T)$,
 $u(x,t) = x V(R,T)$.

If the influence of drugs is considered, see [4, 5, 6], then a more general mathematical model is given in the form;

$$\frac{\partial u(x,t)}{\partial t} = a \frac{\partial^2 u(x,t)}{\partial x^2} + \left[\lambda \ln\left(\frac{\mu}{u(x,t)}\right) - g\left(\nu(s)\right) \right] u(x,t)$$

We perturb the last equation by a multiplicative noise term and consider the following stochastic integral equation;

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$$u(x,t) = f(x) + a \int_{0}^{t} \frac{\partial^{2}u(x,s)}{\partial x^{2}} ds$$

+ $\int_{0}^{t} \left[\lambda \ln \left(\frac{\mu}{u(x,s)} \right) - g(\nu(s)) \right] u(x,s) ds + \sigma \int_{0}^{t} u(x,s) dW(s).$ (6)
Set h (x, t) = X₁ (t) u (x, t) and applying Ito's formula, we get
 $dh(x,t) = a \frac{\partial^{2}h(x,t)}{\partial x^{2}} dt +$

$$+ \left[\lambda \ln \left(\frac{\mu}{h(x,t)} \right) - g \left(\nu(s) \right) + \lambda \sigma W(t) - \frac{\sigma^2}{2} \right] h(x,t) dt + + \int_o^t f(s) ds - \lambda \int_o^t \nu(x,s) ds,$$
(7)
For almost every w in Ω , where

$$f(t) = \lambda \ln \mu - \frac{\sigma^2}{2} - \lambda \sigma W(t) - g(v(s)).$$

Set
$$v(x,t) = ln$$
 $[h(x,t)]$. We get
 $v(x,t) = ln \quad \phi(x) +$
 $+a \int_{0}^{t} \left[\frac{\partial^{2} v(x,s)}{\partial x^{2}} + \left(\frac{\partial v(x,s)}{\partial x} \right)^{2} \right] ds$
 $+ \int_{0}^{t} f(s) ds - \lambda \int_{0}^{t} v(x,s) ds,$ (8)
For almost every w in Ω ,

By a solution of (8), we mean a function v such that v, $\frac{\partial v}{\partial x}$ and $\frac{\partial^2 v}{\partial x^2}$ are continuous on (- ∞ , ∞) X [0, T] and satisfies equation (8) on (- ∞ , ∞) X [0, T], for almost every $\omega \in \Omega$, (see [7,8]).

Theorem (1). If there exists a solution v(x,t) of equation (8) such that $\left|\frac{\partial v(x,t)}{\partial x}\right| \leq M$ on $(-\infty, \infty) \ge [0, T]$ for almost every $\omega \ge \Omega$, where M is a positive constant, then that solution is unique for almost every $\omega \ge \Omega$.

$$\begin{split} v_i(x,t) &= r^{-\lambda t} V_i(x,t), \\ V_3(x,t) &= V_1(x,t) - V_2(x,t), \end{split}$$

where $v_1(x,t)$ and $v_2(x, t)$ are solutions of (8), for almost every $\omega \in \Omega$. It is easy to see that;

$$V_3(x,t) = \int_0^t \int_{-\infty}^{\infty} G(x-y,t,s) \frac{\partial V_3(t,s)}{\partial y} \left[\frac{\partial V_1(y,s)}{\partial y} + \frac{\partial V_2(y,s)}{\partial y} \right] dy ds,$$

Where

$$G(x - y, t, s) = e^{-\lambda s} \frac{e^{\frac{-(y - x)^2}{e^{\frac{4}{4a(t - s)}}}}}{\sqrt{4\pi a(t - s)}}$$

Noticing that $\frac{\partial V_1(x,t)}{\partial x}$ and $\frac{\partial V_2(x,t)}{\partial x}$ are bounded on $(-\infty, \infty)$ X [0, T], thus after simple calculations we get

$$Max \left| \frac{\partial V_3(x,t)}{\partial x} \right| \le \frac{M_3^n}{n!}, n = 1, 2, 3, \dots$$

where $M_3 > 0$ is a constant. Letting $n \rightarrow \infty$, we get

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$$\left|\frac{\partial V_3(x,t)}{\partial x}\right| = 0 \quad on \quad (-\infty,\infty)X[0,t].$$

But $V_3(x,0) = 0$. Thus

 $v_1(x, t) = v_2(x, t)$ on $(-\infty, \infty) X [0, T)$ and for almost every $\omega \in \Omega$. This means that there exists a unique positive solution u(x,t) of equation (6) for almost every $\omega \in \Omega$, (see [8,...,12]).

To solve equation (8), we use the Adomian decomposition method. Assume that the unknown function v can be represented by an infinite series of the form; $v(x,t) = \sum_{i=0}^{\infty} v_i(x,t),$ (9)

and the nonlinear term can be decomposed by an infinite series of polynomials given by

$$\left(\frac{\partial v(x,t)}{\partial x}\right)^2 = \sum_{i=0}^{\infty} A_i(x,t)$$

The function $v_i(x, t)$, I = 0, 1, 2, ... will be determined recurrently, and $A_i(x,t)$ are the so-called Adomian polynomials of $v_0, v_1, v_2, ...$ determined by Determined by

$$A_k(x,t) = \frac{1}{k!} \frac{d^k}{d\eta^k} \left[\frac{\partial}{\partial x} \sum_{i=0}^{\infty} - \eta^i v_i(x,t) \right]_{\eta=0}^2$$

 $k = 0, 1, 2, \ldots$

Equation (8) can be written in the form

$$\nu(x,t) = \stackrel{-\lambda t}{e} ln \phi(x,t) + \int_{0}^{t} e^{\lambda(s-t)} f(s) ds$$
$$+ a \int_{0}^{t} e^{\lambda(s-t)} \left[\frac{\partial^{2} \nu(x,t)}{\partial x^{2}} + \left(\frac{\partial \nu(x,t)}{\partial x} \right)^{2} \right] ds.$$
(10)

Substituting (9) and (10) into (11) and identifying the zero component $v_0(x, t)$ by

 $v_o(x,t) = e^{-\lambda t} ln \phi(x) + \int_0^t e^{\lambda(s-t)} f(s) ds$, then the remaining components can be determined by using the recurrence relation

$$v_n(x,t) = a \int_0^t e^{\lambda(s-t)} \left[\frac{\partial^2 v_n(x,s)}{\partial x^2} + A_n(x,s) \right] ds$$

The Adomian polynomials A_i , $i = 0, 1, 2, \ldots$ are given by

$$A_o(x,t) = \left(\frac{\partial v_o(x,t)}{\partial x}\right)^2,$$

$$A_{1}(x,t) = 2 \frac{\partial v_{o}(x,t)}{\partial x} \frac{\partial v_{1}(x,t)}{\partial x},$$

$$A_{2}(x,t) = \left(\frac{\partial v_{1}(x,t)}{\partial x}\right)^{2} + 2 \frac{\partial v_{o}(x,t)}{\partial x} \frac{\partial v_{2}(x,t)}{\partial x},$$

$$A_{3}(x,t) = 2 \frac{\partial v_{o}(x,t)}{\partial x} \frac{\partial v_{3}(x,t)}{\partial x} + 2 \frac{\partial v_{1}(x,t)}{\partial x} \frac{\partial v_{2}(x,t)}{\partial x}.$$

Notice that;

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$$\sum_{i=0}^{\infty} A_i(x,t) = \sum_{i=0}^{\infty} \left[\frac{\partial v_i(x,t)}{\partial x}\right]^2 + 2\sum_{i\neq j} \frac{\partial v_i(x,t)}{\partial x}\frac{\partial v_i(x,t)}{\partial x}$$

Now the solution of (10) can be represented by; $-\lambda t$

 $v(x,t) = \stackrel{-\lambda t}{e} ln \quad \phi(x) + \int_{o}^{t} e^{\lambda(s-t)} f(s) ds + F(x,t),$ where F is a deterministic function, which is given by

$$F(x,t) = a \int_{O}^{t} e^{\lambda(s-t)} \left[\sum_{i=1}^{\infty} \frac{\partial^{2} v_{i}(x,t)}{\partial x^{2}} + A_{i}(x,s) \right] ds,$$

From the uniqueness of the solution of equation (4) it follows that $v(x,t) = \exp \left[v(x,t) + \sigma W(t)\right]$

$$= exp \quad \left[\stackrel{-\lambda t}{e} ln \phi(x) + F(x,t) + \sigma W(t) + \int_{0}^{t} e^{\lambda(s-t)} f(s) ds \right].$$

Let us compute the expected number E [u(x, t)] of tumor cells u(x, t) at time t > 0 and location x.

$$\sigma \int_{0}^{t} e^{\lambda(s-t)} dW(s)$$

It is clear that the stochastic process *O* is a zero – mean Gaussian process with variance:

$$E\left[\sigma^{2}\left\{\int_{0}^{t} e^{\lambda(s-t)}dW(s)\right\}^{2}\right] = \sigma^{2}E\left[\int_{0}^{t} e^{2\lambda(s-t)}ds\right] = \frac{\sigma^{2}}{2\lambda}\left(1 - e^{-2\lambda t}\right)$$

Consequently

$$E\left[exp \quad \left\{\sigma \int_{0}^{t} e^{\lambda(s-t)}dW(s)\right\}\right] = \frac{\sigma^{2}}{4\lambda}\left(1 - e^{2\lambda t}\right)$$

Supposing that g and v are independent of the process W(t), we get

$$E[u(x,t)] = \\ = \phi^*(x,t)E\left[exp\left\{-\int_0^t e^{\lambda(s-t)}g(\nu(s))ds\right]\right]$$

Where

$$\phi^*(x,t) = \left[\phi(x)\right]^{-\frac{\lambda t}{e}} \left[\mu\right]^{1-\frac{-\lambda t}{e}} exp\left[\frac{\sigma^2}{4\lambda}\left(1-\frac{-2\lambda t}{e}\right) - F^*(x,t)\right],$$
$$F^*(x,t) = \frac{\sigma^2}{2\lambda}\left(1-\frac{-\lambda t}{e}\right) - F(x,t).$$

Theorem 2. If $\phi(x) = e^{-\beta}$, where α and β are constants, then the solution of equation (4) is given by;

$$u(x,t) = \Psi(x,t) \exp \left[\sigma \int_{0}^{t} e^{\lambda(s-t)} dW(s) - \int_{0}^{t} e^{\lambda(s-t)} G(r(s) ds\right],$$

Where

 $\psi(x,t) = [\mu]^{1-e^{-\lambda t}} \exp\left[\left(\alpha x + \beta\right)^{-\lambda t} \frac{1}{2\lambda} \left(2a\alpha^{-\lambda t} - \sigma^{2}\right) \left(1 - \frac{-\lambda t}{e}\right)\right].$ Proof. We have

Vol.8, No.2, pp.40-50, June 2020

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$$v_{1}(x,t) = a \int_{0}^{t} e^{\lambda(s-t)} \left[\frac{\partial^{2} v_{0}(x,s)}{\partial x^{2}} + A_{0}(x,s) \right] ds$$
$$= \frac{a\alpha^{2}}{\lambda} - \frac{\lambda t}{e} \left[1 - \frac{-\lambda t}{e} \right],$$
$$v_{2}(x,t) = a \int_{0}^{t} e^{\lambda(s-t)} \left[\frac{\partial^{2} v_{1}(x,s)}{\partial x^{2}} + 2 \frac{\partial v_{0}(x,s)}{\partial x} \frac{\partial v_{1}(x,s)}{\partial x} \right] ds$$
$$= 0,$$
$$= 0, \quad \text{for } n > 2$$

= 0,So $v_n(x, t) = 0, \text{ for } n \ge 2.$

Hence the required result.

Suppose that g and v are independent of the process W(t). Thus the expected number E [u (x, t)] at time t > 0 and location x is given by :

 $E(x) = \psi(x,t) = exp\left[\frac{\sigma^2}{4\lambda}\left(1 - \frac{-\lambda t}{e}\right) - \int_0^t \frac{-\lambda t}{e}g\left(\nu(s)\right)ds\right].$ The Variance V [μ (x, t)] of the types calls $\mu(x, t)$ of time to

The Variance V [u(x, t)] of the tumor cells u(x, t) at time t > 0 and location x is given by;

$$\begin{aligned} & \forall [u(\mathbf{x}, t)] = \\ &= \psi^2(x, t) \exp \left[-2 \int_0^t e^{\lambda(s-t)} g(\nu(s)) ds \right] \exp[z(t)(z(t) - 1)], \\ & \text{Where:} \\ & z(t) = \frac{\sigma^2}{2\lambda} \left(1 - \frac{-2\lambda t}{e} \right), \\ & (\text{Comp. } [13 - 23]). \end{aligned}$$

CONCLUSION

The suitable mathematical models of stochastic dynamical systems and nonlinear stochastic partial differential equations explore important problems in biology. This tool is an ever increasing towards. The considered models incomporate tumor immune interaction terms of forms that are qualitively different form these commonly used.

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