# ON SOME STOCHASTIC GROWTH MODELS WITH APPLICATIONS 

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#### Abstract

In this paper, we consider some stochastic dynamical systems.The stochastic processes related to these models are some different kinds of tumor cancer cells. The growth and diffusion of brain tumor cancer is also studied by using a nonlinear stochastic diffusion model. The considered models are generalization of some deterministic models. In the frame of these stochastic models we are able to study the growth models for tumor cells under the influence of random perturbations. In general mathematical models help to predict the tumour size and optimize the treatment procedure in deteministic form, there are several models including exponential, dynamical systems, logistic, nonlinear diffusion equations that have been used to describe the behaviour of cancer cell growth amd proliferation. By using the stochastic analysis and the Adomian method we can study more general models. KEYWORDS: stochastic dynamical systems, stochastic diffusion processes, ito integrals, tumor cancer cells, adomian method.


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## INTRODUCTION

Different types of dynamical systems of cancer progression and treatment have already been constructed. For example there are many problems written on the subject of mathematical models in cancer chemotherapy such as Hannelore Liset and David Julitz [1], K.R. Fister and Pannetta [2], J.M. Murrary,[3] and many others. We mension also the papers [4-7]. In this paper, we shall study a stochastic dynamical system and a stochastic diffusion process. In section 2, we shall solve the considered stochastic dynamical sestem. Some properties are also studied. In section 3, we shall solve a nonlinear stochastic partial differential equation. In section 4 a nonlinear stochastic diffusion model related to brain cancer is studied. We shall use Adomian decomposition method to find the stochastic solution.

## A stochastic dynamical system

Let: $\left(\Omega, F,\left(\mathrm{~A}_{\mathrm{t}}\right) \geq 0, \mathrm{P}\right)$ be a filtered probability space. Consider the following stochastic dynamical system.
$d X=b(X) d t+B(X) d W(t)$,
$\mathrm{t} \in\left[0, a_{2}^{-1}\right]$, where; $\quad \mathrm{X}=\left[\begin{array}{l}T \\ N \\ L\end{array}\right]$,
$\mathrm{b}(\mathrm{X})=\left[\begin{array}{c}a_{1} \mathrm{~T}\left(1-a_{2} T\right)-\mathrm{D}(t) \mathrm{T} \\ a_{3}-a_{4} \mathrm{~N}-a_{5} \mathrm{NT} \\ -a_{6} \mathrm{~L}-a_{7} \mathrm{~L} \mathrm{~T}+a_{8} \mathrm{NT}\end{array}\right]$,
$\mathrm{B}(\mathrm{X})=\left[\begin{array}{ccc}\sigma_{1} T & 0 & 0 \\ 0 & \sigma_{2} N & 0 \\ 0 & 0 & \sigma_{3} L\end{array}\right]$,
$\mathrm{W}(\mathrm{t})=\left[\begin{array}{l}W_{1}(t) \\ W_{2}(t) \\ W_{3}(t)\end{array}\right], \quad \sigma_{\mathrm{i}} \in(-\infty, \infty), \mathrm{i}=1,2,3$,
$\mathrm{W}_{1}, \mathrm{~W}_{2}$ and $\mathrm{W}_{3}$ are standared independent Weiner processes adapted to the filteration $\left(A_{t}\right) \geq 0$, See [8].

The stochastic process $\{T(t): t \geq 0\}$ is the tumor cell population at time $t,\{N(t): t \geq 0\}$ is the total level of natural killer cells effectiveness at time $t$ and $\{\mathrm{L}(\mathrm{t}): \mathrm{t} \geq 0\}$ is the total level of tumor specific CD $8^{+} T$ cell effectveness at time $t$, see [ $\left.9-12\right]$.
The parameters $a_{1}, \ldots, a_{8}$ are positive and $\mathrm{D}(\mathrm{t})$ is given by $D(t)=a_{7} \frac{(\mathrm{~L} / \mathrm{T})^{c}}{\mathrm{~s}+(\mathrm{L} / \mathrm{T})^{c}}, \mathrm{c}, \mathrm{s} \geq 0$.

It is supposed that the expectations $\mathrm{E}\left[\mathrm{T}^{2}(0)\right], \mathrm{E}\left[\mathrm{N}^{2}(0)\right]$ and $\mathrm{E}\left[\mathrm{L}^{2}(0)\right]$ exist. It is supposed also that the vector $(T(0), N(0), L(0))$ is independent of $\left(W_{1}(t), W_{2}(t), W_{3}(t)\right)$. We shall find now a representation for $\mathrm{T}(\mathrm{t})$.

Set $\mathrm{T}^{*}=\mathrm{T}^{-1}$ and using the stochastic chain rule of Ito, we get:
$\mathrm{dT}^{*}=\left[a_{1} a_{2}+\left(\sigma_{1}^{2}-a_{1}+\mathrm{D}(\mathrm{t})\right) \mathrm{T}^{*}\right] \mathrm{dt}-\sigma_{1} \mathrm{~T}^{*} \mathrm{dW}_{1}(\mathrm{t})$.
Thus;
$\mathrm{T}^{*}(\mathrm{t})=\mathrm{T}^{-1}(0) \exp \left[\sigma_{1} \mathrm{~W}_{1}(\mathrm{t})-\frac{1}{2} \sigma_{1}^{2} \mathrm{t}+\int_{0}^{t} f(\theta) \mathrm{d} \theta\right]+$
$a_{1} a_{2} \int_{0}^{t} \exp \left[\sigma_{1}\left\{W_{1}(t)-W_{1}(\theta)\right\} \frac{1}{2} \sigma_{1}^{2}(\mathrm{t}-\theta)+\int_{\theta}^{t} f(r) \mathrm{dr}\right] d \theta$,
Where; $\quad \mathrm{f}(\mathrm{r})=\sigma_{1}^{2}-a_{1}+\mathrm{D}(\mathrm{r})$
Notice that $\mathrm{T}^{*}(\mathrm{t})$ is almost surely, a.s., positive,
Thus

$$
\mathrm{T}(\mathrm{t})=\mathrm{T}^{*-1}(\mathrm{t})
$$

The total level of the natural killer cells $\mathrm{N}(\mathrm{t})$, is given by:

$$
\begin{aligned}
\mathrm{N}(\mathrm{t}) & =\mathrm{N}(0) \exp \left[\sigma_{2} \mathrm{~W}_{2}(\mathrm{t})-a_{4} \mathrm{t}-\frac{1}{2} \sigma_{2}^{2} \mathrm{t}-a_{5} \int_{0}^{t} T(\theta)\right] \mathrm{dt} \\
& +a_{3} \int_{0}^{t} \exp \left[\sigma_{2}\left\{W_{2}(t)-W_{2}(\theta)\right\}-a_{4}(\mathrm{t}-\theta)-\frac{1}{2} \sigma_{2}^{2}(\mathrm{t}-\theta)-a_{5} \int_{\theta}^{t} T(r) \mathrm{dr}\right] \mathrm{dt}
\end{aligned}
$$

The total level $\mathrm{L}(\mathrm{t})$ of tumor specific CD $8^{+}$is given by:

$$
\begin{aligned}
& \mathrm{L}(\mathrm{t})=\mathrm{L}(0) \exp \left[\sigma_{3} \mathrm{~W}_{3}(\mathrm{t})-a_{7} \int_{0}^{t} T(\theta) \mathrm{dt}-a_{6} \mathrm{t}-\frac{1}{2} \sigma^{2} \mathrm{t}\right] \\
& +\quad \int_{0}^{t} a_{8} \mathrm{~N}(\theta) \mathrm{T}(\theta)\left[\exp \sigma_{3}\left(W_{3}(t)-W_{3}(\theta)\right)-a_{7} \int_{\theta}^{t} T(r) \mathrm{dr}-a_{6}(\mathrm{t}-\theta)-\right.
\end{aligned}
$$

$$
\left.\frac{1}{2} \sigma^{2}(\mathrm{t}-\theta)\right] \mathrm{d} \theta
$$

Let us study the case when;
$\mathrm{s}=0$, Notice that the processes
$\mathrm{W}_{1}(\mathrm{t}), \mathrm{W}_{1}(\mathrm{t})-\mathrm{W}_{1}(\mathrm{~s}), \mathrm{T}(0)$ are independent and
$\mathrm{E}\left[e^{\sigma_{i} W_{1}(t)}\right]=\exp \left[\frac{\sigma_{i}^{2}}{2} \mathrm{t}\right]$,
$\mathrm{E}\left[e^{\sigma_{i}\left(W_{1}(t)-W_{i}(s)\right.}\right]=\exp \left[\frac{(t-s) \sigma_{i}^{2}}{2}\right], \quad \mathrm{i}=1,2,3$
Thus;

$$
E\left[T^{-1}(t)\right]=\mathrm{e}^{\left(a_{7}-a_{1}+\sigma_{1}^{2}\right) t} E\left[T^{-1}(0)\right]+\frac{a_{1} a_{2}}{a_{7}-a_{1}+\sigma_{1}^{2}}\left[e^{\left(a_{7}-a_{1}+\sigma_{1}^{2}\right) t}-1\right]
$$

It is clear that
$\mathrm{T}(\mathrm{t}) \leq \mathrm{T}(0) \exp \left[\sigma_{1} W_{1}(t)+\frac{1}{2} \sigma_{1}^{2} t-\int_{0}^{t} f(\theta) \mathrm{d} \theta\right]$.
Thus;
$\mathrm{E}[\mathrm{T}(\mathrm{t})] \leq \mathrm{E}(\mathrm{T}(0)) e^{\left(a_{1}-a_{7}\right) \mathrm{t}}$.
If $a_{2}=0$, we get
$\mathrm{T}(\mathrm{t})=\mathrm{T}(0) \exp \left[\sigma_{1} W_{1}(t)+\frac{1}{2} \sigma_{1}^{2} t-\int_{0}^{t} f(\theta) \mathrm{d} \theta\right]$.
If $a_{2}=\mathrm{s}=0$, we get
$\mathrm{E}\left(\mathrm{T}^{2}(\mathrm{t})\right)=\mathrm{E}\left(\mathrm{T}^{2}(0)\right) \exp \left[\sigma_{1}^{2} \mathrm{t}+2\left(a_{1}-a_{7}\right) t\right]$.
Notice that $T(\mathrm{t})$ and $\mathrm{W}_{2}(\mathrm{t})$ are independent, thus
$\mathrm{E}[\mathrm{N}(\mathrm{t})]=e^{-t a_{4}} \mathrm{E}(N(0)) \mathrm{E}\left[\exp \left\{-a_{5} \int_{0}^{t} \mathrm{~T}(\theta) \mathrm{d} \theta\right\}\right]$
$+a_{3} \int_{0}^{t} e^{-a_{4}(t-\theta)} \mathrm{E}\left[\exp \left\{-a_{5} \int_{\theta}^{t} T(r) \mathrm{dr}\right\}\right] \mathrm{d} \theta$.
It is easy to see that
$\mathrm{E}[\mathrm{N}(\mathrm{t})] \leq e^{-t a_{7}} \mathrm{E}[N(0)]+\frac{a_{3}}{a_{3}}\left[1-e^{-t a_{4}}\right]$.
The product $\mathrm{N}(\mathrm{t}) \mathrm{T}(\mathrm{t})$ and $\mathrm{W}_{3}(\mathrm{t})$ and also $\mathrm{T}(\mathrm{t})$ are indepent, thus
$\mathrm{E}[\mathrm{L}(\mathrm{t})]=\mathrm{E}[\mathrm{L}(0)] e^{-a_{6} t} \mathrm{E}\left[-a_{7} \int_{\theta}^{t} T(\theta) \mathrm{d} \theta\right]$

$$
+a_{8} \int_{\theta}^{t} \mathrm{E}\left[N(\theta) \mathrm{T}(\theta) \exp \left\{-a_{7} \int_{\theta}^{t} T(r) \mathrm{dr}\right\}\right] \mathrm{e}^{a_{6}(t-\theta)} \mathrm{d} \theta
$$

## A nonlinear stochastic diffusion model

In this section, we shall study the following nonlinear stochastic diffusion model;

$$
\begin{gathered}
u(\mathrm{x}, \mathrm{t})=\mathrm{f}(x)+\int_{0}^{t} a(x) \mathrm{u}(\mathrm{x}, \mathrm{~s}) \frac{\partial}{\partial x}\left[\frac{1}{u(\mathrm{x}, \mathrm{~s})} \frac{\partial \mathrm{u}(\mathrm{x}, \mathrm{~s})}{\partial x}\right] \mathrm{ds} \\
+\int_{0}^{t}\left[\lambda \ln \frac{\mu}{u(x, s)}-\mathrm{g}(v(s))\right] u(\mathrm{x}, \mathrm{~s}) \mathrm{ds}+ \\
+\sigma \int_{0}^{t} \mathrm{u}(\mathrm{x}, \mathrm{~s}) \mathrm{d} W(s)
\end{gathered}
$$

Where $\mathrm{W}(\mathrm{t})$ is a standard Wiener process adapted to the filteration $\left(\mathrm{A}_{\mathrm{t}}\right)_{\mathrm{t} \geq 0}, \sigma \in(-\infty, \infty)$, $\lambda$ and $\mu$ are positive parameters, $\mathrm{f}(x)$ and $a(x)$ are given continuous bounded functions defined on $(-\infty, \infty)$. It is supposed that $a(x)$ is positive for all $\mathrm{x} \in(-\infty, \infty)$.
It is supposed also that $g$ and $v$ are maps from $(0, \infty) \times \Omega$ to $(0, \infty)$, that are measurable and adapted to the filtration $\left(\mathrm{A}_{\mathrm{t}}\right)_{\mathrm{t} \geq 0}$ and are a.s., locally bounded.

The stochastic process $\{\mathrm{u}(\mathrm{x}, \mathrm{t}):-\infty<\mathrm{x}<\infty, \mathrm{t}>0\}$ may be thought as the concentration of brain cancer tumor cells at a location $x$ and time $t, u(x, 0)=f(x)$ represents the initial deterministic state.
Consider the following two Brownian motions:
$\mathrm{X}_{1}(\mathrm{t})=\exp [-\sigma \mathrm{W}(\mathrm{t})], \mathrm{X}_{2}(\mathrm{t})=\exp [\sigma \mathrm{W}(\mathrm{t})]$.
It is easy to see that:
$\mathrm{d} \mathrm{X}_{1}(\mathrm{t})=\frac{\sigma^{2}}{2} \mathrm{X}_{1}(t) \mathrm{dt}-\sigma \mathrm{X}_{1}(t) \mathrm{d} W(t)$,
$\mathrm{d} \mathrm{X}_{2}(\mathrm{t})=\frac{\sigma^{2}}{2} \mathrm{X}_{2}(t) \mathrm{dt}+\sigma \mathrm{X}_{2}(t) \mathrm{d} W(t)$,
$\mathrm{X}_{1}(0)=\mathrm{X}_{2}(0)=1$.
Set $u^{*}(x, t)=X_{1}(t) u(x, t)$ and applying Ito's product rule formula, we get
$d u^{*}(x, t)=X_{1} d u(x, t)+u(x, t) d X_{1}-\sigma^{2} X_{1} u(x, t) d t$.
Thus;
$\frac{1}{u_{*}^{*}(x, t)} \frac{\partial u^{*}(x, t)}{\partial t}=a(x) \frac{\partial}{\partial x}\left[\frac{1}{u^{*}(x, t)} \frac{\partial u^{*}(x, t)}{\partial x}\right]+\mathrm{F}(\mathrm{t})-\lambda \ln \left(\mathrm{u}^{*}(\mathrm{x}, \mathrm{t})\right)$,
$\mathrm{u}^{*}(\mathrm{x}, 0)=\mathrm{f}(\mathrm{x})$,
Where;
$\mathrm{F}(\mathrm{t})=\frac{-\sigma^{2}}{2}+\lambda \ln \mu-\mathrm{g}(v(t))-\lambda \sigma W(t)$.
Set $\mathrm{v}(\mathrm{x}, \mathrm{t})=\mathrm{e}^{\lambda \mathrm{t}} \mathrm{u}^{*}(\mathrm{x}, \mathrm{t})$, one gets:

$$
\frac{\partial v(x, t)}{\partial t}=a(x) \frac{\partial^{2} v(x, t)}{\partial x^{2}}+\mathrm{e}^{\lambda t} \mathrm{~F}(t)
$$

$\mathrm{v}(\mathrm{x}, 0)=\ln \mathrm{f}(\mathrm{x})$
Thus; $v(x, t)$ is given by
$v(\mathrm{x}, \mathrm{t})=\int_{-\infty}^{\infty} G(\mathrm{x}, \mathrm{y}, \mathrm{t}) \ln \mathrm{f}(\mathrm{y}) \mathrm{dy}+$
$+\int_{0}^{t} \int_{-\infty}^{\infty} G(\mathrm{x}, \mathrm{y}, \mathrm{t}-\mathrm{s}) \mathrm{e}^{\lambda s} \mathrm{~F}(s) \mathrm{dy} d s$.

Where G is the fundamental solution of the equation
$\frac{\partial u}{\partial t}=a(x) \frac{\partial^{2} u}{\partial x^{2}}$.
Since $\int_{-\infty}^{\infty} G(x, y, t)$ dy $=1$, it follows that
$v(\mathrm{x}, \mathrm{t})=\int_{-\infty}^{\infty} G(x, y, t) \ln \mathrm{f}(y) \mathrm{dy}+\int_{0}^{t} e^{\lambda s} \mathrm{~F}(s) \mathrm{ds}$,
So;
$u(x, t)=\exp \left[\sigma W(t)+e^{-\lambda t} v(x, t)\right]$,
For a.s., $\omega \in \Omega$, and all $\mathrm{t} \geq 0,-\infty<\mathrm{x}<\infty$. Thus we can find a subset $\Omega^{*} \subset \Omega$, with P $\left(\Omega^{*}\right)=1$, such that formula (2) is valid for all $\omega \in \Omega^{*}, \mathrm{t} \geq 0,-\infty<\mathrm{x}<\infty$.
It is clear that
$\mathrm{W}(\mathrm{t})=\int_{0}^{t} e^{\lambda(\mathrm{s}-\mathrm{t})} \mathrm{d} W(s)+\lambda \int_{0}^{t} e^{\lambda(s-t)} W(s) \mathrm{ds}$,
for all $\mathrm{W} \in \Omega^{*}$.
From (2) and (3) one gets
$\mathrm{u}(\mathrm{x}, \mathrm{t})=\exp \left[V(t)-\int_{0}^{t} e^{\lambda(\mathrm{s}-\mathrm{t})} \mathrm{g}(v, \mathrm{~s}) \mathrm{ds}+\mathrm{H}(\mathrm{x}, \mathrm{t})\right]$,
Where
$\mathrm{V}(\mathrm{t})=\sigma \int_{0}^{t} e^{\lambda(\mathrm{s}-\mathrm{t})} \mathrm{d} W(\mathrm{~s})$,
$\mathrm{H}(\mathrm{x}, \mathrm{t})=e^{-\lambda t} \int_{-\infty}^{\infty} \mathrm{G}(\mathrm{x}, \mathrm{y}, \mathrm{t}) \ln \mathrm{f}(\mathrm{y}) \mathrm{dy}+\left[\frac{\sigma^{2}}{2}\left(1-\mathrm{e}^{-\lambda t)}\right] \ln \mu\right.$.
Notice that $\mathrm{V}(\mathrm{t})$ is a Gausian process with mean zero. The variance of $\mathrm{V}(\mathrm{t})$ is given by $\mathrm{E}\left[V^{2}(t)\right]=\mathrm{E}\left[\sigma^{2} \int_{0}^{t} e^{\lambda(\mathrm{s}-\mathrm{t})} \mathrm{d} W(s)\right]^{2}=\sigma^{2} \int_{0}^{t} e^{2 \lambda(\mathrm{~s}-\mathrm{t})} \mathrm{ds}=$ $=\frac{\sigma^{2}}{2 \lambda}\left(1-\mathrm{e}^{-2 \lambda t}\right)$.
Thus;
$\mathrm{E}\left[e^{V(t)}\right]=\frac{1}{\sqrt{2 \pi \gamma(t)}} \int_{-\infty}^{\infty} e^{x} \mathrm{e}^{\frac{-\mathrm{x}^{2}}{2 \gamma(t)}} \mathrm{dx}=\exp \left[\frac{\gamma(t)}{2}\right]$,
where;
$\gamma(t)=\frac{\sigma^{2}}{2 \lambda}\left[1-\mathrm{e}^{-2 \lambda t}\right]$.
If g and $\gamma$ are independent of W , then the expected number of tumor cells is given by
$\mathrm{E}[\mathrm{u}(\mathrm{x}, \mathrm{t})]=\mathrm{E}\left[\exp \left\{\frac{1}{2} \gamma(t)+\mathrm{H}(\mathrm{x}, \mathrm{t})\right\}\right] \mathrm{E}\left[\exp \left\{-\int_{0}^{t} e^{\lambda(\mathrm{s}-\mathrm{t})} \mathrm{g}(\gamma(s)) \mathrm{ds}\right\}\right]$.
It can be also compute all the moments of the stochastic process $\{\mathrm{u}(\mathrm{x}, \mathrm{t})\}$ :
$e^{-\mathrm{nH}(\mathrm{x}, \mathrm{t})} \mathrm{E}\left[u^{n}(\mathrm{x}, \mathrm{t})\right]=$
$=E\left[\exp \left\{\frac{1}{2} n^{2} \gamma(t)\right\}\right] E\left[\exp \left\{\int_{0}^{t} n \mathrm{e}^{\lambda(\mathrm{s}-\mathrm{t})} \mathrm{g} \mathrm{ds}\right\}\right]$.

## A brain cancer model

Let $\mathrm{V}(\mathrm{R}, \mathrm{T})$ be the concentration of brain tumor cells at a location R and time T . Consider now the Burgers equation;
$\frac{\partial V(R, T)}{\partial T}=\frac{D}{R^{2}} \frac{\partial}{\partial R}\left[R^{2} \frac{\partial V(R, T)}{\partial R}\right]-(p-k) F(T) V(R, T)$.
Where D is the diffusion coefficients, (estimated at $0.0013 \mathrm{Cm}^{2}$ per day for glioblastoma multiform).
The constants p and k represent proliferations rate and killing rate respectively, ( R measures the distance from the origin of glioblastoma). The function $\mathrm{F}(\mathrm{T})$ describes to the temporal profile of the treatment.
Equation (5) can be written in the form
$\frac{\partial u(x, t)}{\partial t}=a \frac{\partial^{2} u(x, t)}{\partial x^{2}}-c(t) u(x, t)$,
where $\mathrm{t}=(\mathrm{p}-\mathrm{k}) \mathrm{T}, \mathrm{p}>\mathrm{k}$,
$x=\sqrt{\frac{a(p-k)}{D}} R, \quad c(t)=F(T)$,
$u(x, t)=x V(R, T)$.
If the influence of drugs is considered, see $[4,5,6]$, then a more general mathematical model is given in the form;
$\frac{\partial u(x, t)}{\partial t}=a \frac{\partial^{2} u(x, t)}{\partial x^{2}}+\left[\lambda \ln \left(\frac{\mu}{u(x, t)}\right)-g(v(s))\right] u(x, t)$.
We perturb the last equation by a multiplicative noise term and consider the following stochastic integral equation;

$$
\begin{gather*}
u(x, t)=f(x)+a \int_{o}^{t} \frac{\partial^{2} u(x, s)}{\partial x^{2}} d s \\
+\int_{o}^{t} \quad\left[\lambda \ln \left(\frac{\mu}{u(x, s}\right)-g(v(s))\right] u(x, s) d s+\sigma \int_{o}^{t} u(x, s) d W(s) . \tag{6}
\end{gather*}
$$

Set $\mathrm{h}(\mathrm{x}, \mathrm{t})=\mathrm{X}_{1}(\mathrm{t}) \mathrm{u}(\mathrm{x}, \mathrm{t})$ and applying Ito's formula, we get
$d h(x, t)=a \frac{\partial^{2} h(x, t)}{\partial x^{2}} d t+$
$+\left[\lambda \ln \left(\frac{\mu}{h(x, t)}\right)-g(v(s))+\lambda \sigma W(t)-\frac{\sigma^{2}}{2}\right] h(x, t) d t+$
$+\int_{o}^{t} f(s) d s-\lambda \int_{o}^{t} \quad v(x, s) d s$,
For almost every w in $\Omega$,
where

$$
f(t)=\lambda \ln \mu-\frac{\sigma^{2}}{2}-\lambda \sigma W(t)-g(v(s))
$$

Set $\quad v(x, t)=\ln \quad[h(x, t)]$. We get

$$
\begin{align*}
& +a \int_{o}^{t}\left[\frac{\partial^{2} v(x, s)}{\partial x^{2}}+\left(\frac{\partial v(x, s)}{\partial x}\right)^{2}\right] d s \\
& +\int_{o}^{t} f(x, t)=\ln \quad \phi(x)+ \\
& +\lambda \int_{o}^{t} v(x, s) d s, \tag{8}
\end{align*}
$$

For almost every w in $\Omega$,
By a solution of (8), we mean a function $v$ such that $v, \frac{\partial v}{\partial x}$ and $\frac{\partial^{2} v}{\partial x^{2}}$ are continuous on ($\infty, \infty) \mathrm{X}[0, \mathrm{~T}]$ and satisfies equation (8) on $(-\infty, \infty) \mathrm{X}[0, \mathrm{~T}]$, for almost every $\omega \varepsilon \Omega$, (see [7,8]).
Theorem (1). If there exists a solution $v(x, t)$ of equation (8) such that $\left|\frac{\partial v(x, t)}{\partial x}\right| \leq M$ on $(-\infty, \infty) \mathrm{x}[\mathrm{O}, \mathrm{T}]$ for almost every $\omega \varepsilon \Omega$, where M is a positive constant, then that solution is unique for almost every $\omega \varepsilon \Omega$.
Proof. Set

$$
\begin{aligned}
& V_{i}(x, t)=r^{-\lambda t} V_{i}(x, t), \\
& V_{3}(x, t)=V_{1}(x, t)-V_{2}(x, t),
\end{aligned}
$$

where $v_{1}(\mathrm{x}, \mathrm{t})$ and $\mathrm{v}_{2}(\mathrm{x}, \mathrm{t})$ are solutions of (8), for almost every $\omega \varepsilon \Omega$.
It is easy to see that;

$$
V_{3}(x, t)=\int_{o}^{t} \int_{-\infty}^{\infty} G(x-y, t, s) \frac{\partial V_{3}(t, s)}{\partial y}\left[\frac{\partial V_{1}(y, s)}{\partial y}+\frac{\partial V_{2}(y, s)}{\partial y}\right] d y d s
$$

Where

$$
G(x-y, t, s)=e^{-\lambda s} \frac{e^{\frac{-(y-x)^{2}}{4 a(t-s)}}}{\sqrt{4 \pi a(t-s)}}
$$

Noticing that $\frac{\partial V_{1}(x, t)}{\partial x}$ and $\frac{\partial V_{2}(x, t)}{\partial x}$ are bounded on $(-\infty, \infty) X[0$, T], thus after simple calculations we get

$$
\operatorname{Max}\left|\frac{\partial V_{3}(x, t)}{\partial x}\right| \leq \frac{M_{3}^{n}}{n!}, n=1,2,3, \ldots \ldots
$$

where $\mathrm{M}_{3}>0$ is a constant.
Letting $\mathrm{n} \rightarrow \infty$, we get

$$
\left|\frac{\partial V_{3}(x, t)}{\partial x}\right|=0 \text { on }(-\infty, \infty) X[0, t] .
$$

But $V_{3}(x, 0)=0$. Thus
$v_{1}(\mathrm{x}, \mathrm{t})=v_{2}(\mathrm{x}, \mathrm{t})$ on $(-\infty, \infty) \mathrm{X}[0, \mathrm{~T})$ and for almost every $\omega \varepsilon \Omega$.
This means that there exists a unique positive solution $u(x, t)$ of equation (6) for almost every $\omega \varepsilon \Omega$, (see $[8, \ldots, 12]$ ).
To solve equation (8), we use the Adomian decomposition method. Assume that the unknown function v can be represented by an infinite series of the form;
$v(x, t)=\sum_{i=o}^{\infty} \quad v_{i}(x, t)$,
and the nonlinear term can be decomposed by an infinite series of polynomials given by

$$
\left(\frac{\partial v(x, t)}{\partial x}\right)^{2}=\sum_{i=0}^{\infty} A_{i}(x, t) .
$$

The function $v_{i}(x, t), I=0,1,2, \ldots$. will be determined recurrently, and $\mathrm{A}_{\mathrm{i}}(\mathrm{x}, \mathrm{t})$ are the so-called Adomian polynomials of $v_{0}, v_{1}, v_{2}, \ldots \ldots$ determined by Determined by

$$
A_{k}(x, t)=\frac{1}{k!} \frac{d^{k}}{d \eta^{k}}\left[\frac{\partial}{\partial x} \sum_{i=0}^{\infty} \quad \eta^{i} v_{i}(x, t)\right]_{\eta=0}^{2}
$$

$\mathrm{k}=0,1,2, \ldots$
Equation (8) can be written in the form

$$
\begin{gather*}
v(x, t)={ }^{-\lambda t} \ln \phi(x, t)+\int_{o}^{t} e^{\lambda(s-t)} f(s) d s \\
+a \int_{o}^{t} e^{\lambda(s-t)}\left[\frac{\partial^{2} v(x, t)}{\partial x^{2}}+\left(\frac{\partial v(x, t)}{\partial x}\right)^{2}\right] d s . \tag{10}
\end{gather*}
$$

Substituting (9) and (10) into (11) and identifying the zero component $v_{0}(x, t)$ by $v_{o}(x, t)=\stackrel{-\lambda t}{e} \ln \phi(x)+\int_{o}^{t} \quad e^{\lambda(s-t)} f(s) d s$, then the remaining components can be determined by using the recurrence relation

$$
v_{n}(x, t)=a \int_{o}^{t} e^{\lambda(s-t)}\left[\frac{\partial^{2} v_{n}(x, s)}{\partial x^{2}}+A_{n}(x, s)\right] d s
$$

The Adomian polynomials $\mathrm{A}_{\mathrm{i}}, \mathrm{i}=0,1,2, \ldots \ldots$ are given by

$$
\begin{aligned}
& A_{o}(x, t)=\left(\frac{\partial v_{o}(x, t)}{\partial x}\right)^{2}, \\
& A_{1}(x, t)=2 \frac{\partial v_{o}(x, t)}{\partial x} \frac{\partial v_{1}(x, t)}{\partial x}, \\
& A_{2}(x, t)=\left(\frac{\partial v_{1}(x, t)}{\partial x}\right)^{2}+2 \frac{\partial v_{o}(x, t)}{\partial x} \frac{\partial v_{2}(x, t)}{\partial x}, \\
& A_{3}(x, t)=2 \frac{\partial v_{o}(x, t)}{\partial x} \frac{\partial v_{3}(x, t)}{\partial x}+2 \frac{\partial v_{1}(x, t)}{\partial x} \frac{\partial v_{2}(x, t)}{\partial x} .
\end{aligned}
$$

Notice that;

$$
\sum_{i=0}^{\infty} A_{i}(x, t)=\sum_{i=0}^{\infty}\left[\frac{\partial v_{i}(x, t)}{\partial x}\right]^{2}+2 \sum_{i \neq j} \frac{\partial v_{i}(x, t)}{\partial x} \frac{\partial v_{i}(x, t)}{\partial x}
$$

Now the solution of (10) can be represented by;

$$
v(x, t)=-\frac{-\lambda t}{e} \ln \quad \phi(x)+\int_{o}^{t} \quad e^{\lambda(s-t)} f(s) d s+F(x, t)
$$

where F is a deterministic function, which is given by

$$
F(x, t)=a \int_{O}^{t} e^{\lambda(s-t)}\left[\sum_{i=1}^{\infty} \frac{\partial^{2} v_{i}(x, t)}{\partial x^{2}}+A_{i}(x, s)\right] d s
$$

From the uniqueness of the solution of equation (4) it follows that $v(x, t)=\exp \lfloor v(x, t)+\sigma W(t)\rfloor$

$$
=\exp \left[-\frac{-\lambda t}{e} \ln \phi(x)+F(x, t)+\sigma W(t)+\int_{0}^{t} e^{\lambda(s-t)} f(s) d s\right]
$$

Let us compute the expected number $E[u(x, t)]$ of tumor cells $u(x, t)$ at time $t>0$ and location $x$.

It is clear that the stochastic process $\sigma \int_{O} e^{\lambda(s)}$ is a zero - mean Gaussian process with variance:

$$
E\left[\sigma^{2}\left\{\int_{0}^{t} e^{\lambda(s-t)} d W(s)\right\}^{2}\right]=\sigma^{2} E\left[\int_{0}^{t} e^{2 \lambda(s-t)} d s\right]=\frac{\sigma^{2}}{2 \lambda}\left(1-e^{-2 \lambda t}\right)
$$

Consequently

$$
E\left[\exp \left\{\sigma \int_{0}^{t} e^{\lambda(s-t)} d W(s)\right\}\right]=\frac{\sigma^{2}}{4 \lambda}\left(1-e^{2 \lambda t}\right)
$$

Supposing that $g$ and $v$ are independent of the process $\mathrm{W}(\mathrm{t})$, we get

$$
\begin{aligned}
& E[u(x, t)]= \\
& =\phi^{*}(x, t) E\left[\exp \left\{-\int_{0}^{t} e^{\lambda(s-t)} g(v(s)) d s\right]\right.
\end{aligned}
$$

Where

$$
\begin{aligned}
\phi^{*}(x, t) & =[\phi(x)]^{-\lambda t}[\mu]^{1--\lambda t} e \exp \left[\frac{\sigma^{2}}{4 \lambda}\left(1-\frac{-2 \lambda t}{e}\right)-F^{*}(x, t)\right] \\
F^{*}(x, t) & =\frac{\sigma^{2}}{2 \lambda}\left(1-\frac{-\lambda t}{e}\right)-F(x, t)
\end{aligned}
$$

Theorem 2. If $\phi(x)=\stackrel{e}{e}$, where $\alpha$ and $\beta$ are constants, then the solution of equation (4) is given by;

$$
u(x, t)=\Psi(x, t) \exp \left[\sigma \int_{0}^{t} e^{\lambda(s-t)} d W(s)-\int_{0}^{t} e^{\lambda(s-t)} G(r(s) d s]\right.
$$

Where
$\psi(x, t)=[\mu]^{1-e^{-\lambda t}} \exp \left[(\alpha x+\beta) e^{-\lambda t} \frac{1}{2 \lambda}\left(2 a \alpha e^{-\lambda t}-\sigma^{2}\right)(1-\stackrel{-\lambda t}{e})\right]$.
Proof. We have

$$
\begin{aligned}
& v_{1}(x, t)=a \int_{o}^{t} e^{\lambda(s-t)}\left[\frac{\partial^{2} v_{o}(x, s)}{\partial x^{2}}+A_{o}(x, s)\right] d s \\
& =\frac{a \alpha^{2}}{\lambda} e^{-\lambda t}\left[1-\frac{-\lambda t}{e}\right], \\
& v_{2}(x, t)=a \int_{o}^{t} e^{\lambda(s-t)}\left[\frac{\partial^{2} v_{1}(x, s)}{\partial x^{2}}+2 \frac{\partial v_{o}(x, s)}{\partial x} \frac{\partial v_{1}(x, s)}{\partial x}\right] d s \\
& =0,
\end{aligned}
$$

So $v_{n}(x, t)=0$, for $n \geq 2$.
Hence the required result.
Suppose that $g$ and $v$ are independent of the process $W(t)$. Thus the expected number $\mathrm{E}[\mathrm{u}(\mathrm{x}, \mathrm{t})]$ at time $\mathrm{t}>0$ and location x is given by :
$\mathrm{E}(\mathrm{x})=\psi(x, t)=\exp \left[\frac{\sigma^{2}}{4 \lambda}\left(1-{ }^{-\lambda t}\right)-\int_{o}^{t}{ }^{-\lambda t} g(v(s)) d s\right]$.
The Variance $\mathrm{V}[\mathrm{u}(\mathrm{x}, \mathrm{t})$ ] of the tumor cells $\mathrm{u}(\mathrm{x}, \mathrm{t})$ at time $\mathrm{t}>0$ and location x is given by;
$\mathrm{V}[\mathrm{u}(\mathrm{x}, \mathrm{t})]=$
$=\psi^{2}(x, t) \exp \quad\left[-2 \int_{o}^{t} e^{\lambda(s-t)} g(v(s)) d s\right] \exp [z(t)(z(t)-1)]$,
Where:
$z(t)=\frac{\sigma^{2}}{2 \lambda}(1-\stackrel{-2 \lambda t}{e})$,
(Comp. [13-23]).

## CONCLUSION

The suitable mathematical models of stochastic dynamical systems and nonlinear stochastic partial differential equations explore important problems in biology. This tool is an ever increasing towards. The considrered models incomporate tumor immune interaction terms of forms that are qualitively different form these commonly used.

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